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Open book and open notes

Show your work for credit and place boxes around your answers.

1. Find the Zero-Input Response (ZIR) of the system described by

$$y[n] - 2r \cdot \cos(\omega_0) y[n-1] + r^2 \cdot y[n-2] = r \cdot \sin(\omega_0) x[n-1]$$

Where r and ω_0 are real values, r < 1, and the following states set for the output

$$y[0] = 0, y[n = -1] = -r^{-1} \cdot \sin(\omega_0), y[n = -2] = -r^{-2} \cdot \sin(2\omega_0)$$