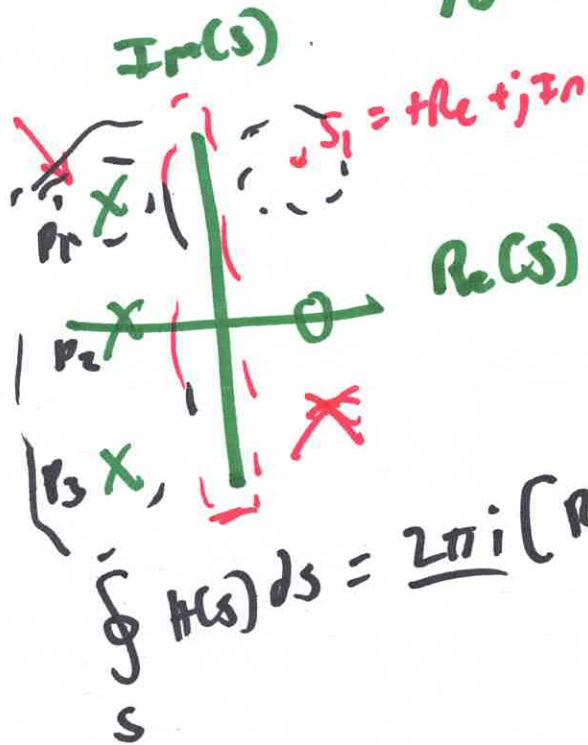


# The Laplace Transform (pt. 2)

$$p_1 = -\alpha_e + j\alpha_m$$

Nov 7<sup>th</sup>, 2020



$$y(t) = H(s) e^{s_1 t}$$

$$y_1(t) = H(s_1) e^{s_1 t}$$

$$(-\alpha_e + j\alpha_m) t$$

$$y_{p_1}(t) = H(s_{p_1}) e^{s_{p_1} t}$$

$$\oint_S H(s) ds = 2\pi i (\text{Residue}_1 + \text{Res}_2 + \text{Res}_3)$$

$$\int \left[ \frac{d^2}{dt^2} y(t) + 7 \frac{dy(t)}{dt} + 12y(t) = \frac{d^2 x(t)}{dt^2} + 3 \frac{dx(t)}{dt} + 2x(t) \right]$$

LTI diff eqns



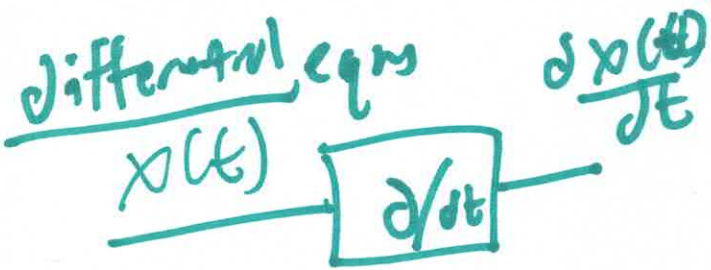
$$q_1(n+1) = \text{Current inputs} + \text{Current Stats}$$

LTI ss eqns



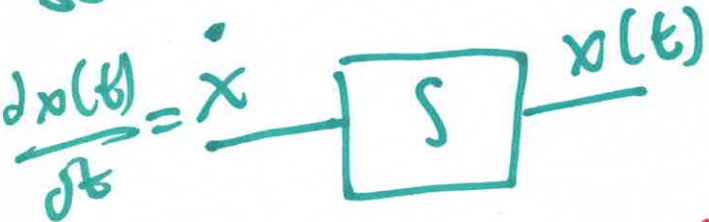
$$y(n) = \text{" + "}$$

Differential eqns



$$\int \left[ \frac{dy(t)}{dt} + 7y(t) + 12 \int y(t) = \frac{dx(t)}{dt} + 3x(t) + 2 \int x(t) \right]$$

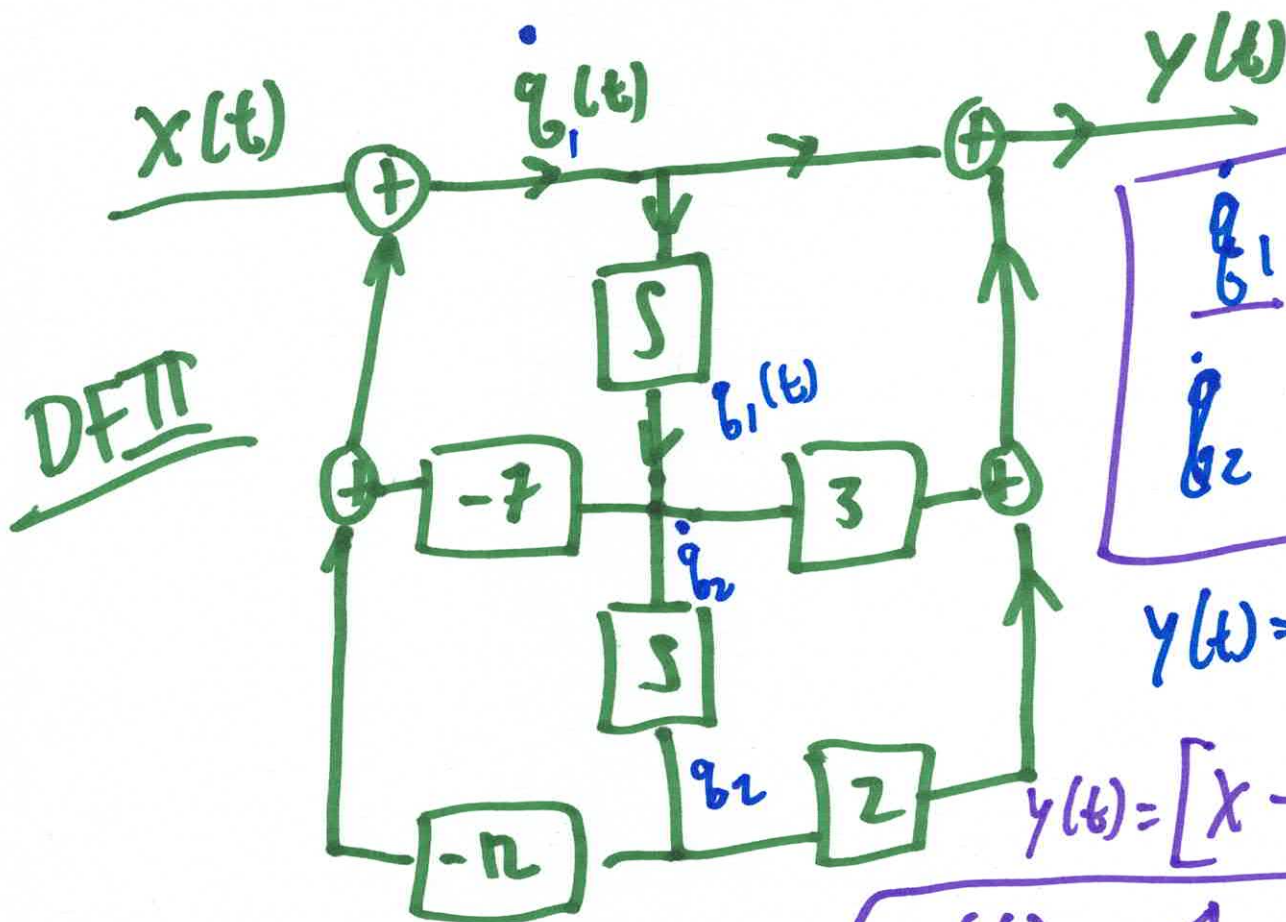
ss



$$y(t) + 7 \int y(t) + 12 \iint y(t) = x(t) + 3 \int x(t) + 2 \iint x(t)$$

$$\underline{y(t)} + 7 \int y + 12 \iint y = x(t) + 3 \int x + 2 \iint x$$

$$y(t) = x(t) + \underline{3 \int x} + \underline{2 \iint x} - \underline{7 \int y} - \underline{12 \iint y}$$



$$\begin{aligned} \dot{q}_1 &= x(t) - 7q_1(t) - 12q_2(t) \\ \dot{q}_2 &= b_1(t) \end{aligned}$$

$$y(t) = \dot{q}_1 + 3q_1(t) + 2q_2(t)$$

$$y(t) = [x - 7q_1 - 12q_2] + 3q_1 + 2q_2$$

$$y(t) = -4q_1 - 10q_2 + x$$

$$\dot{q}_1 = x(t) - 7q_1 - 12q_2$$

$$\dot{q}_2 = q_1$$

$$y = -4q_1 - 10q_2 + x$$

$$q(t) \rightarrow s \text{ } Q(s)$$

sti

$$sQ = A Q + Bx$$

$$Q[sI - A] = Bx$$

$$Q(s) = [sI - A]^{-1} Bx$$

$$Y(s) = H(s) X(s)$$

$$\begin{bmatrix} \dot{q}_1(t) \\ \dot{q}_2(t) \end{bmatrix} = \begin{bmatrix} -7 & -12 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} q_1(t) \\ q_2(t) \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} x(t)$$

$\dot{q}$                        $A$                        $q$                        $B$                        $x$

$$Y(s) = \begin{bmatrix} -4 & -10 \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \end{bmatrix} + \begin{bmatrix} 1 \end{bmatrix} x(t)$$

$y$                        $C$                        $q$                        $D$                        $x$

SS eqns / model

$$Y(s) = C Q(s) + D X(s)$$

$$Y(s) = C [ [sI - A]^{-1} B X(s) ] + D X(s)$$

$$Y(s) = \{ C [sI - A]^{-1} B + D \} X(s)$$

$$A = \begin{bmatrix} -7 & -12 \\ 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

~~Y(s) =~~

$$C = [-4 \ -10] \quad D = 1$$

$$Y(s) = \left\{ [-4 \ -10] \left[ s \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} -7 & -12 \\ 1 & 0 \end{bmatrix} \right] \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 1 \end{bmatrix} \right\} X(s)$$

$$= \left\{ [-4 \ -10] \begin{bmatrix} s+7 & 12 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 1 \right\} X$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\frac{1}{(s+7)s - 12(-1)} \begin{bmatrix} s & -12 \\ +1 & s+7 \end{bmatrix}$$

$$\left[ \frac{1}{s^2 + 7s + 12} \right]$$

17 poles (s)

$$y(s) = \left\{ \overset{1 \times 2}{[-4 \ -10]} \underset{\substack{\uparrow \\ \text{constant}}}{H_{\text{pols}}(s)} \begin{bmatrix} \overset{2 \times 2}{s^2} & -12 \\ 1 & \overset{2 \times 1}{s+7} \end{bmatrix} \begin{bmatrix} \overset{2 \times 1}{1} \\ 0 \end{bmatrix} + 1 \right\} x$$

$$= \left\{ \overset{1 \times 2}{[-4 \ -10]} H_{\text{pols}}(s) \begin{bmatrix} \overset{2 \times 1}{s} \\ 1 \end{bmatrix} + 1 \right\} x$$

$$\frac{y(s)}{x(s)} = \left\{ H_{\text{pols}}(s) (-4s - 10) + 1 \right\} \frac{x(s)}{x(s)}$$

$$H(s) = H_{\text{pols}}(s) (-4s - 10) + 1$$

$$H(s) = \frac{-4s - 10}{s^2 + 7s + 12} + 1$$

$$\frac{-4s - 10}{s^2 + 7s + 12} = \frac{A}{(s+4)} + \frac{B}{(s+3)}$$

$$(s+4)(s+3)$$

$$\frac{-4s - 10}{(s+4)(s+3)} = \frac{A(s+3)}{(s+4)(s+3)} + \frac{B(s+4)}{(s+4)(s+3)}$$

$$s: -4 = A + B$$

$$A = -6$$

s=0 DC

$$H(s) = \frac{-6}{s+4} + \frac{2}{s+3} + \frac{1}{s}$$

$$\underline{s = -3}$$

$$+12 - 10 = 0 + B$$

$$\boxed{B = 2}$$

$$\underline{H(s) = \frac{-6}{s+4} + \frac{2}{s+3} + \frac{1}{s}}$$

$$H(t) = \left[ -6e^{-4t} + 2e^{-3t} + \delta(t) \right] v(t)$$

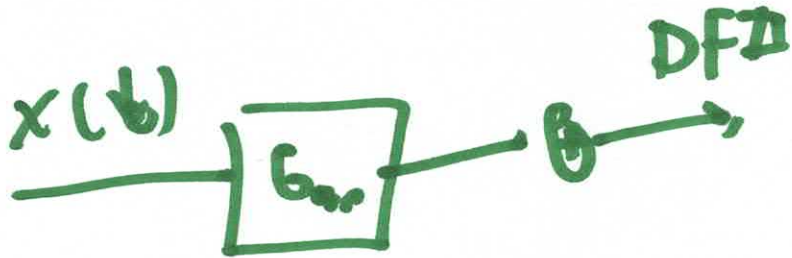
$$H(s) = \frac{s^2 + 3s + 2}{s^2 + 7s + 12}$$

$s \rightarrow \infty$

Gain

$$= \frac{2}{12} = \frac{1}{6}$$

$$\frac{1}{6} \approx 0.1666$$



$$h(t=0) = -6 + 2 + \infty = -4$$

$$= sX + s^2 X$$

