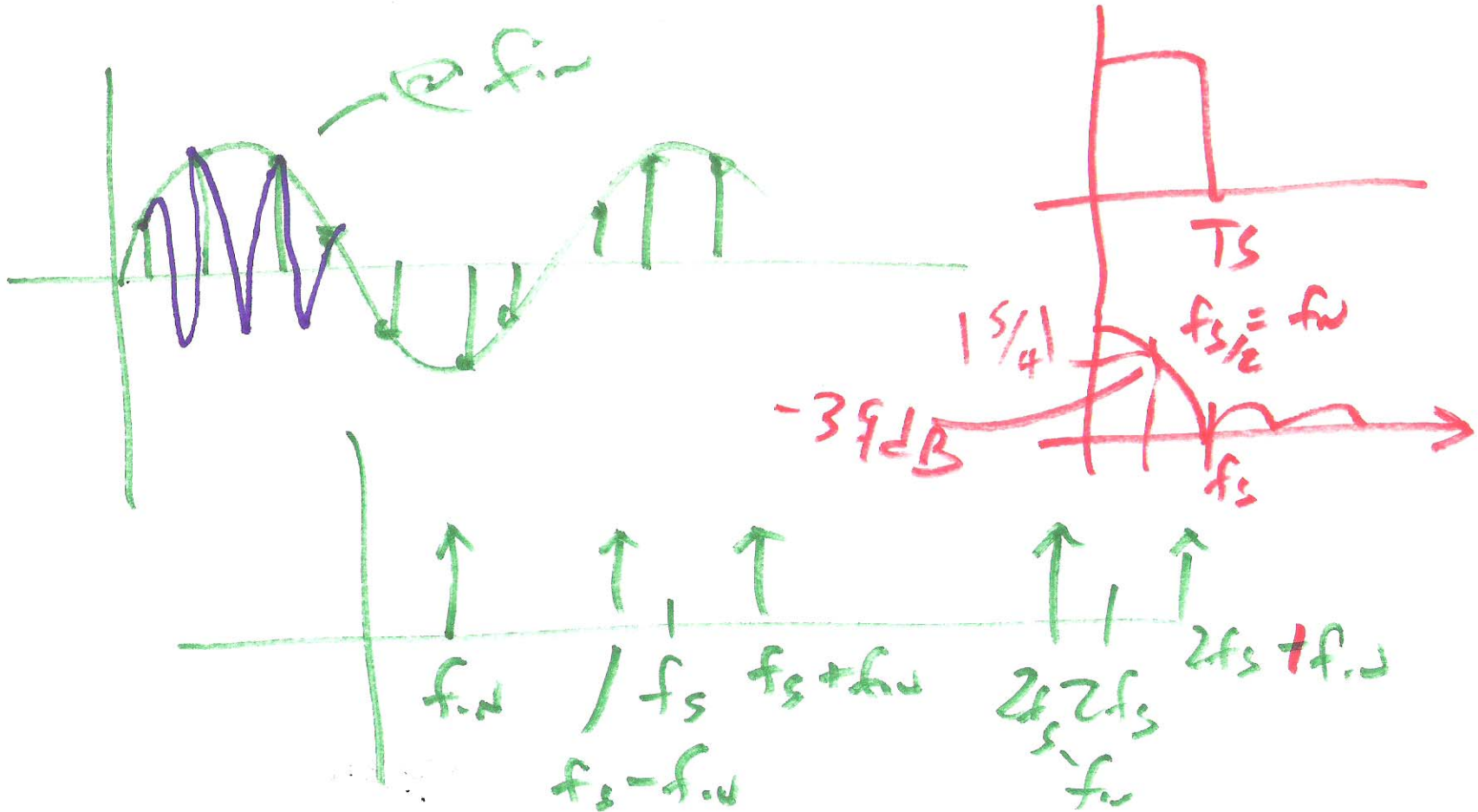


ECG 721

Implementing the S/H

Sept. 22, 2014

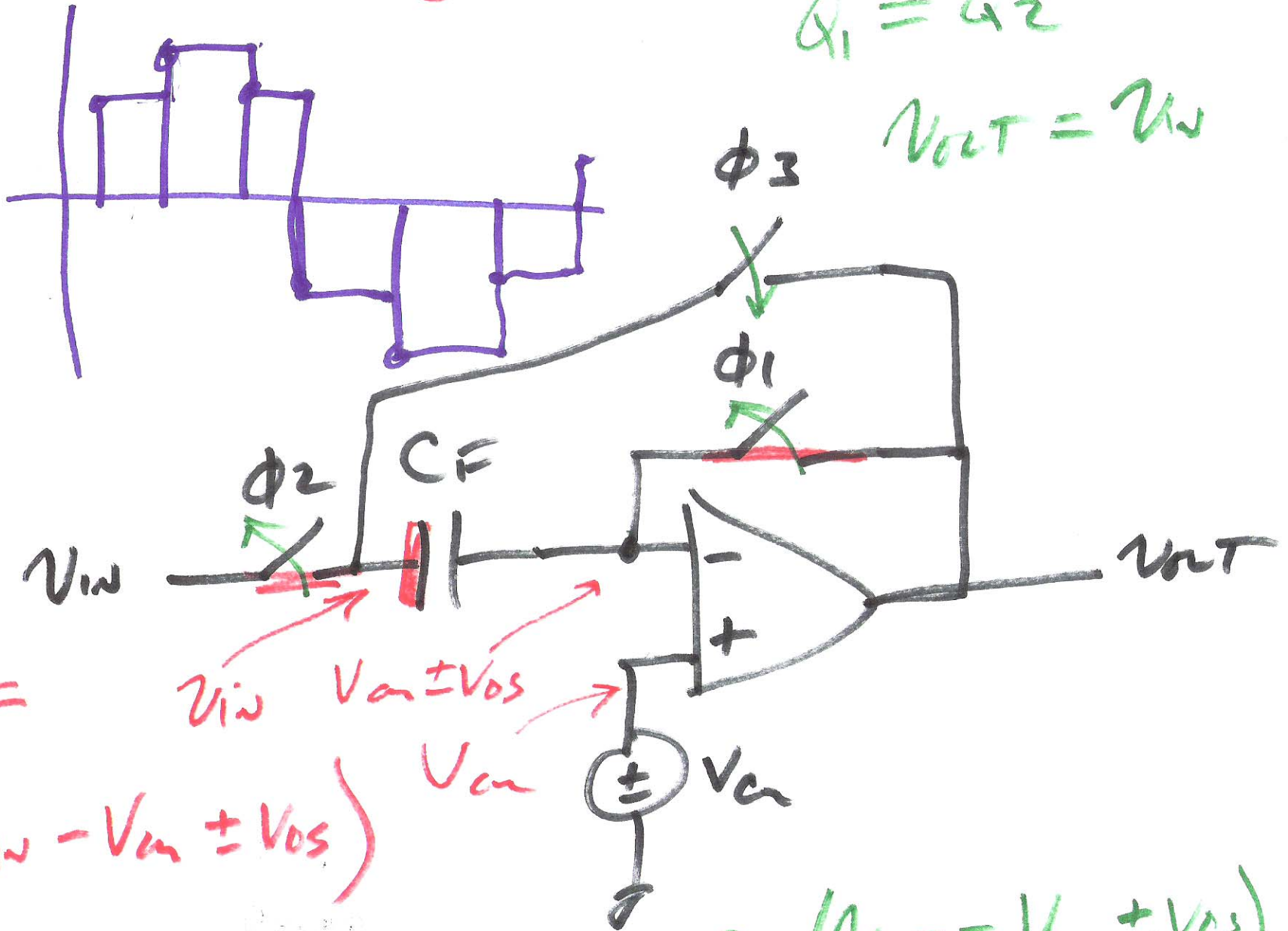


1)

$$CV = Q$$

$$Q_1 = Q_2$$

$$V_{OUT} = V_{IN}$$



$$Q_1 =$$

$$C_F (V_{IN} - V_{cn} \pm V_{OS})$$

$$V_{cn}$$

$$V_{cn}$$

$$C_F (V_{IN} - V_{cn} \pm V_{OS})$$

$$Q_2 = C_F (V_{OUT} - V_{cn} \pm V_{OS})$$

2)

VDD = 1

GND

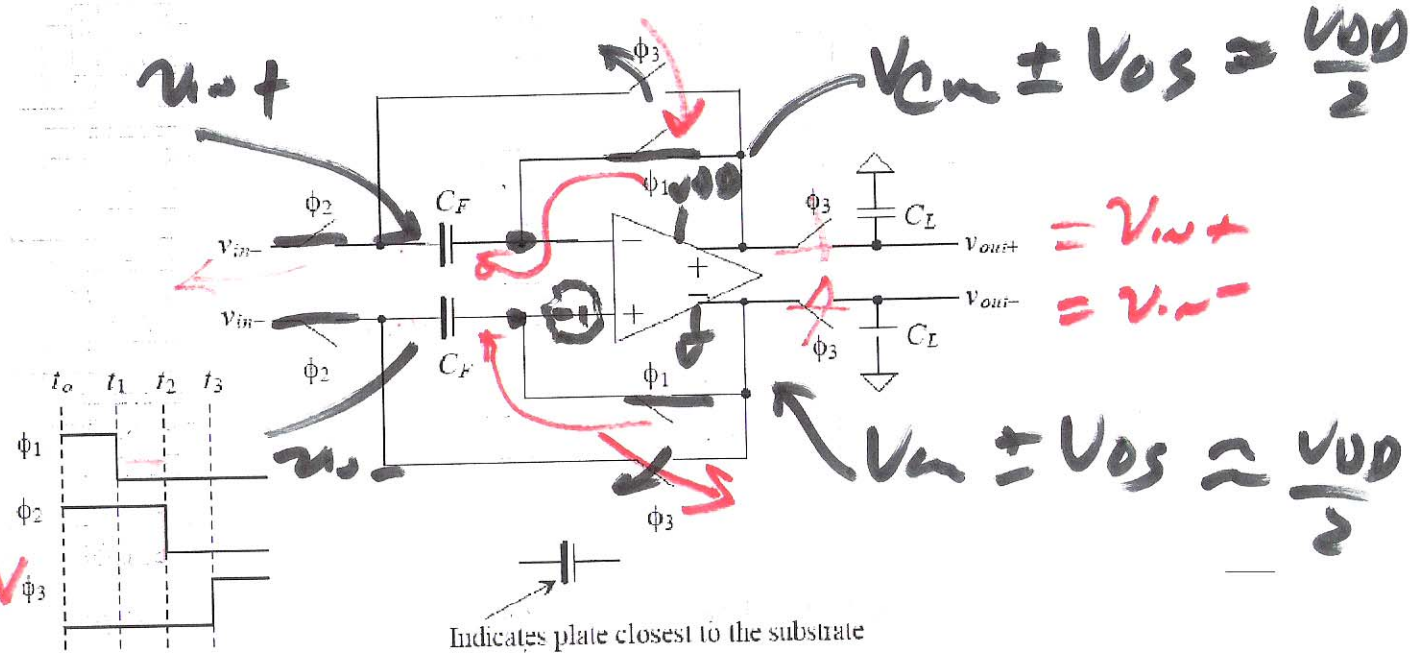
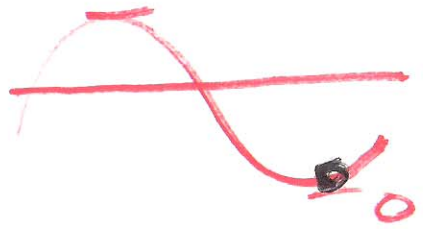
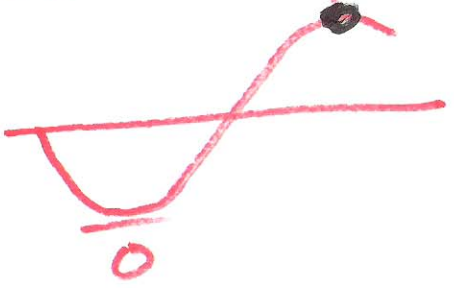


Figure 2.39 Fully-differential S/H differential topology.

v_{in+} 1V



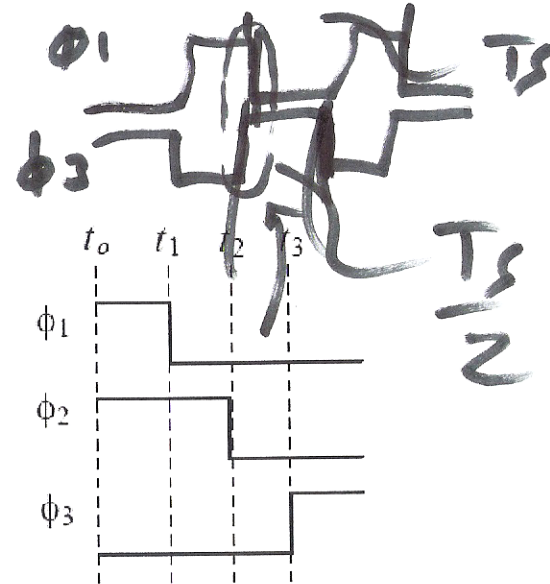
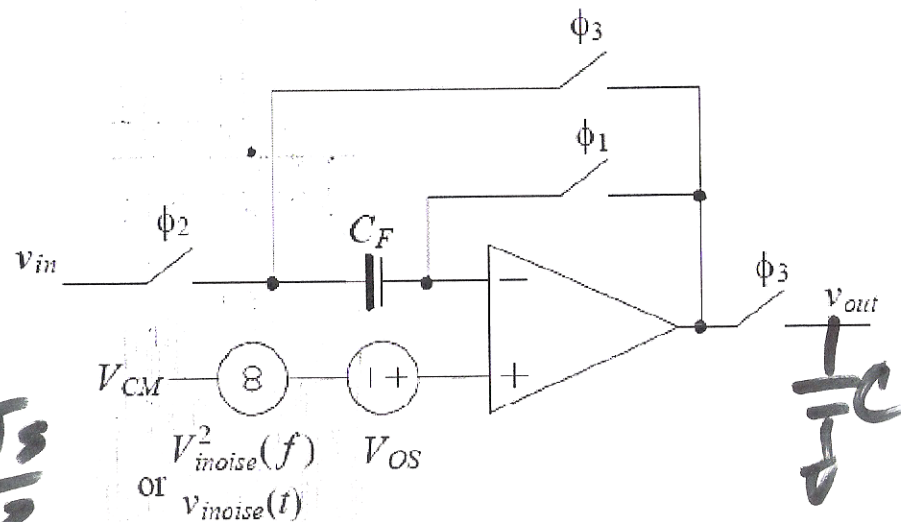
v_{in-}



$$v_{in} = v_{in+} - v_{in-} = 1 - 0 = 1V$$

$$0 - 1 = -1V$$

3)



$$t_3 = t_2 + \frac{T_s}{2}$$

Figure 2.41 S/H with input-referred offset and noise shown.

$$Q_F^{\phi_1} = C_F (V_{in}(t_3) - V_{CM} \pm V_{OS} - V_{noise}(t_3))$$

$$Q_F^{\phi_3} = C_F (V_{out}(t) - V_{CM} \pm V_{OS} - V_{noise}(t))$$

$$V_{out}(t) = V_{in}(t_3) + V_{noise}(t) - V_{noise}(t_3)$$

$$V_{out}(f) \cdot e^{-j2\pi ft} = V_{in}(f) e^{-j2\pi ft_3} + V_{noise}(f) (e^{-j2\pi ft} - e^{-j2\pi ft_3})$$

4)

$$V_{out}(f) = \underbrace{V_{in}(f)}_{\text{noise}} \left(1 - e^{-j2\pi f \frac{T_s}{2}} \right)$$

$$1 - z^{-1/2}$$

$$\left| \frac{V_{out}(f)}{V_{in}(f)} \right| = 2 \left| \sin \pi f_s \cdot \frac{T_s}{2} \right|$$

Noise Transfer Function

$$\left| \frac{V_{onoise}}{V_{inoise}} \right| = 2 \cdot \left| \sin \frac{\pi}{2} \cdot f \cdot T_s \right|$$

assuming clock signals have a near 50% duty cycle.

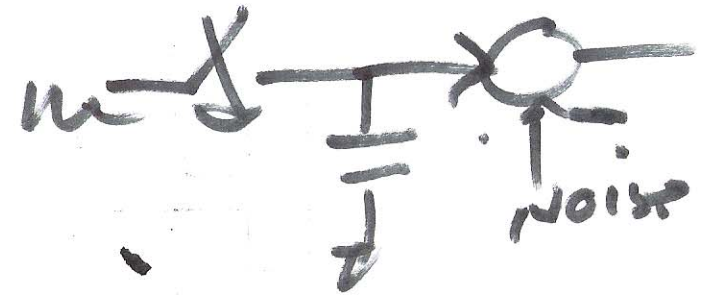
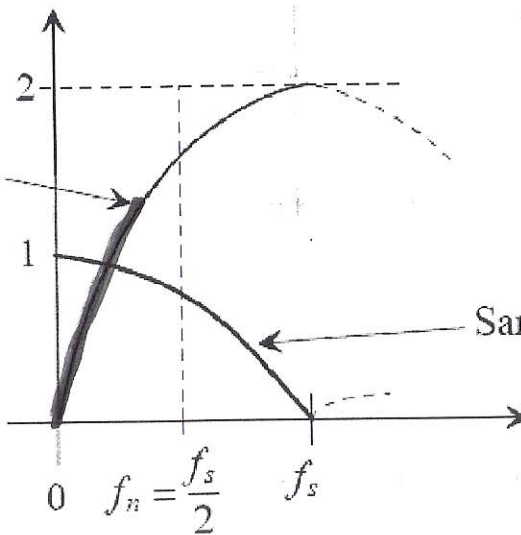


Figure 2.42 The noise transfer function of a S/H.

Autozero followed S/H
is
called Correlated Double
(CDS) Sampling.

6)

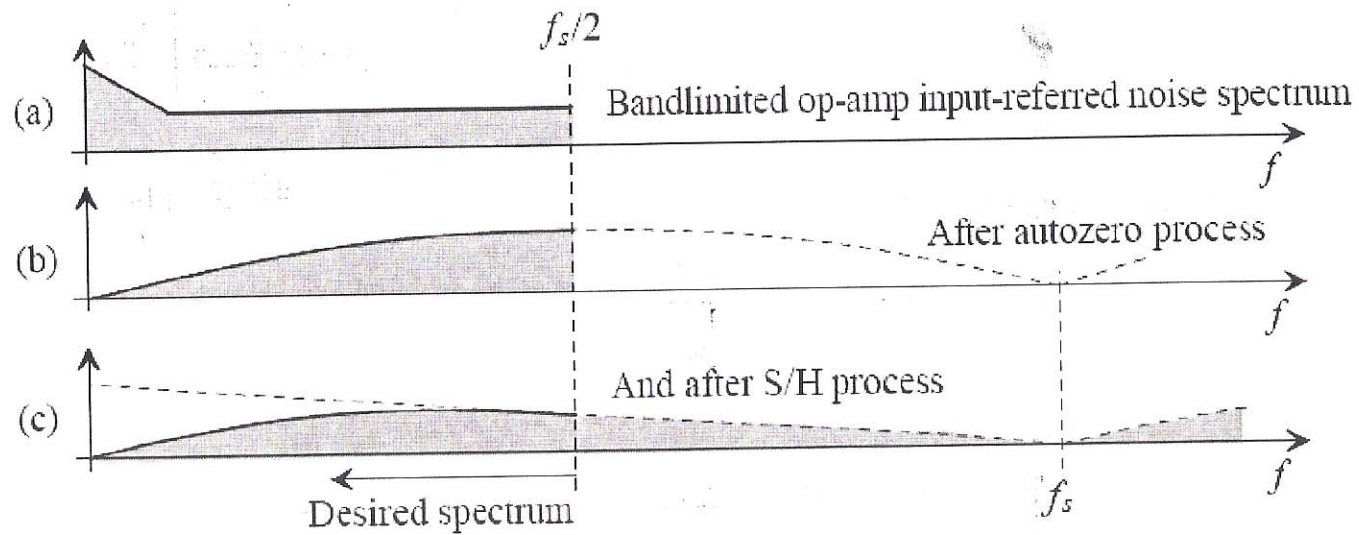


Figure 2.43 Example spectrums when S/H in Fig. 2.39 is used.

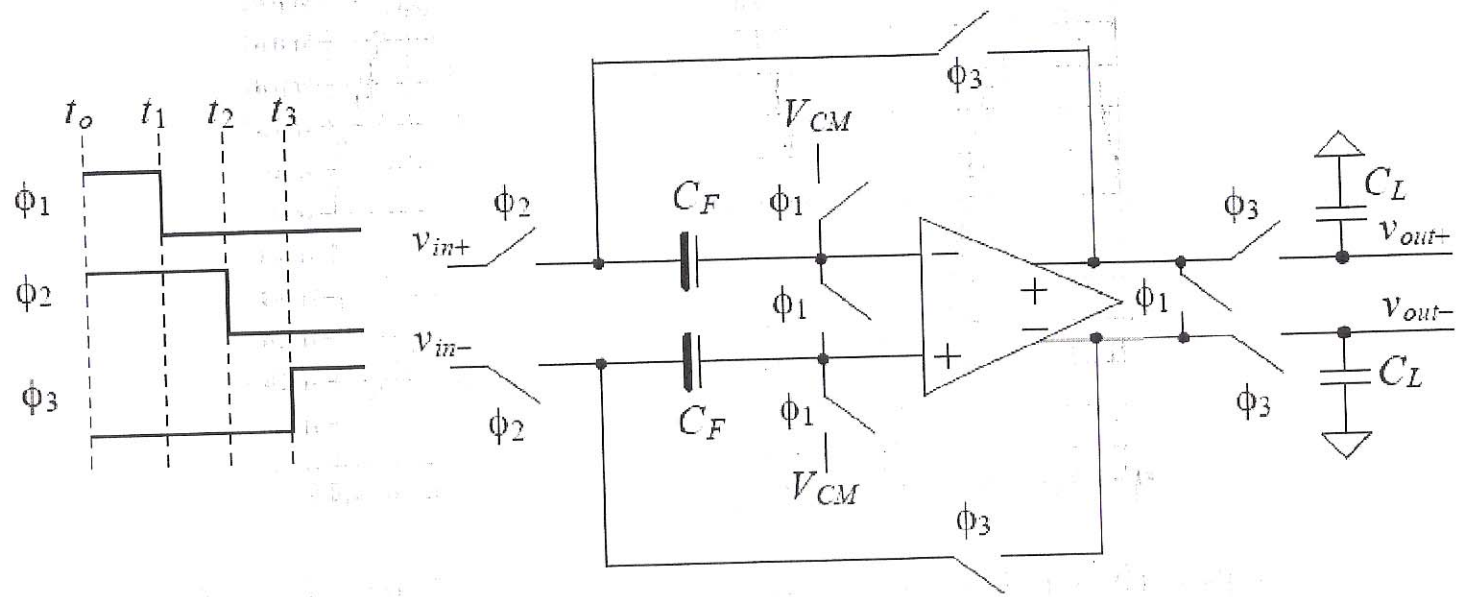


Figure 2.45 Fully-differential S/H differential topology without using CDS.

8)

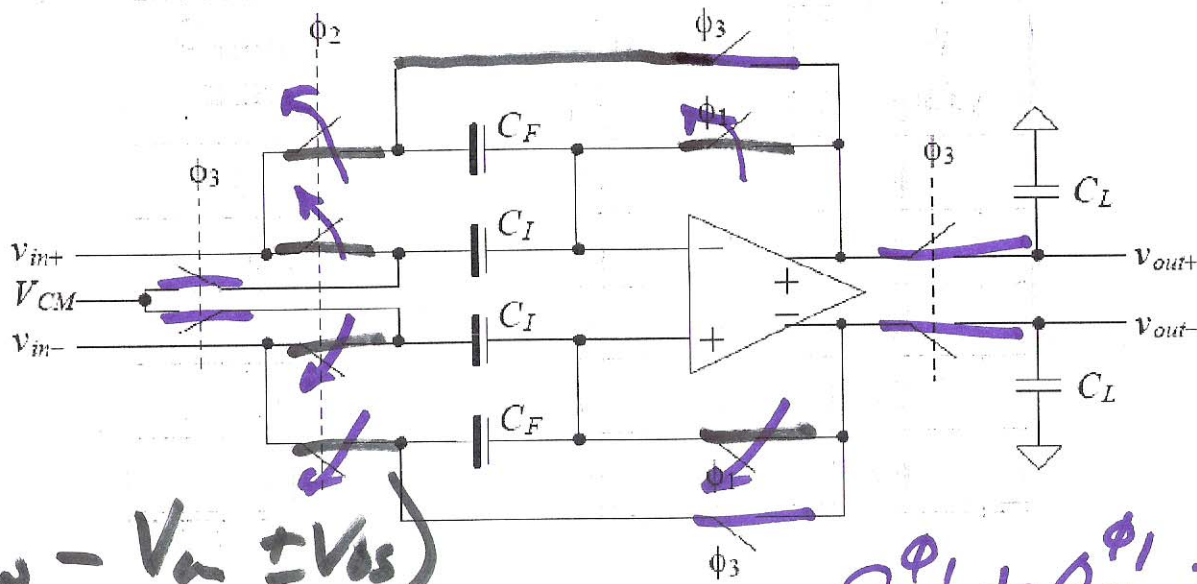


Figure 2.46 A S/H with gain.

$$Q_I^{\phi_1} = C_I (V_{in} - V_m \pm V_{os})$$

$$Q_F^{\phi_1} = C_F (V_{in} - V_m \pm V_{os})$$

$$Q_I^{\phi_1} + Q_F^{\phi_1} = Q_I^{\phi_3} + Q_F^{\phi_3}$$

$$(C_I + C_F) (V_{in} - V_m \pm V_{os})$$

$$Q_I^{\phi_3} = C_I (V_m - V_m \pm V_{os}) = C_I (\pm V_{os})$$

$$Q_F^{\phi_3} = C_F (V_{out} - V_{in} \pm V_{os})$$

$$C_I (\pm V_{os}) + C_F$$

$$(V_{in} - V_m \pm V_{os})$$

$$C_I V_{in} - C_I V_{out} \pm \cancel{C_F V_{os}} + C_F V_{in} - \cancel{C_F V_{out}} \pm \cancel{C_F V_{os}}$$

$$= \cancel{C_I (\pm V_{os})} + C_F (V_{in}) - \cancel{C_F V_{out}} \pm \cancel{C_F V_{os}}$$

$$V_{out} = \frac{C_I}{C_F} V_{in} + V_{in} - \frac{C_I}{C_F} V_{out}$$

for full diff

$$\frac{V_{out}}{V_{in}} = 1 + \frac{C_I}{C_F}$$

10)

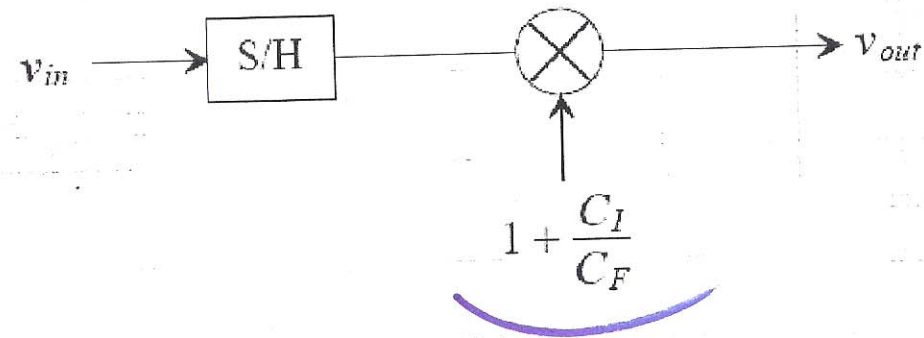


Figure 2.47 Block diagram for the S/H of Fig. 2.46.

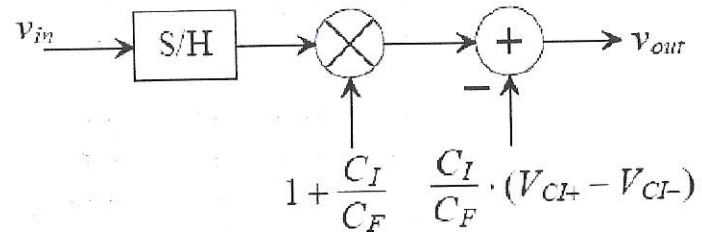
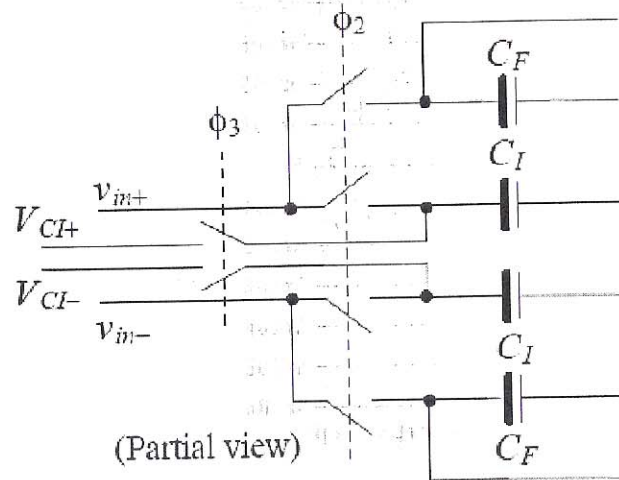


Figure 2.49 Implementing subtraction in the S/H.

12)