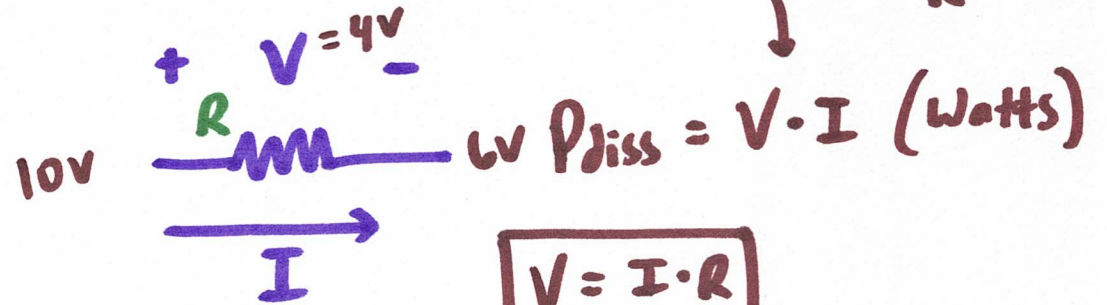


# EE 220: Circuits I [Exam Review 1]

- Thevenin & Norton examples ✓
- mesh analysis / superposition ✓
- AC steady state analysis (phasor problems)
- Dependent sources ✓
- charge sharing ✓
- caps (DC open) & inductors (DC short) ✓
- AC signals (sinusoids)
- power dissipation ✓

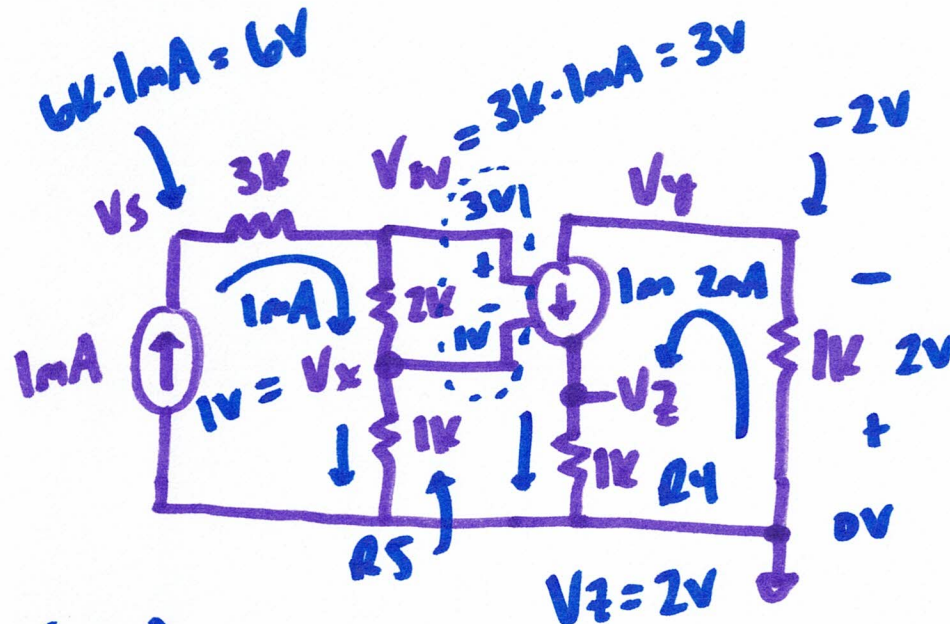
# power dissipation

$$V \cdot \frac{V}{R} = \frac{V^2}{R} = P$$



$$V = I \cdot R$$

## MT P.6

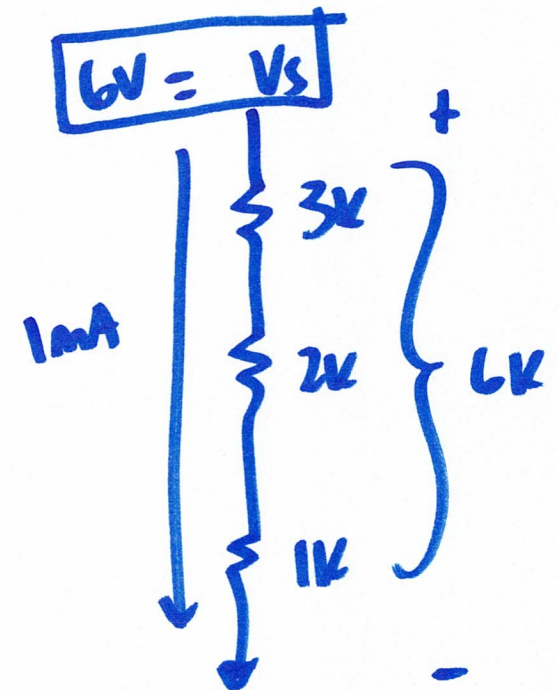


$$P(R_5) = 1V \cdot 1mA = 1mW$$

$$V(R_4) = V_Z = 2V$$

$$I(R_4) = 2mA$$

$$2V \cdot 2mA = 4mW$$



X

LC oscillations  
Caps & inductors in DC

$$\omega = \frac{1}{\sqrt{LC}}$$

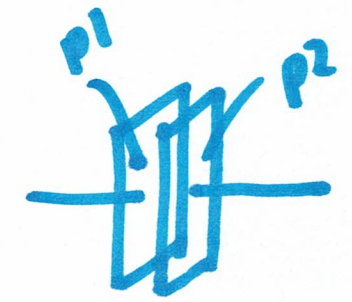
$$\frac{1}{2\pi\sqrt{LC}} = f$$

 in DC = open

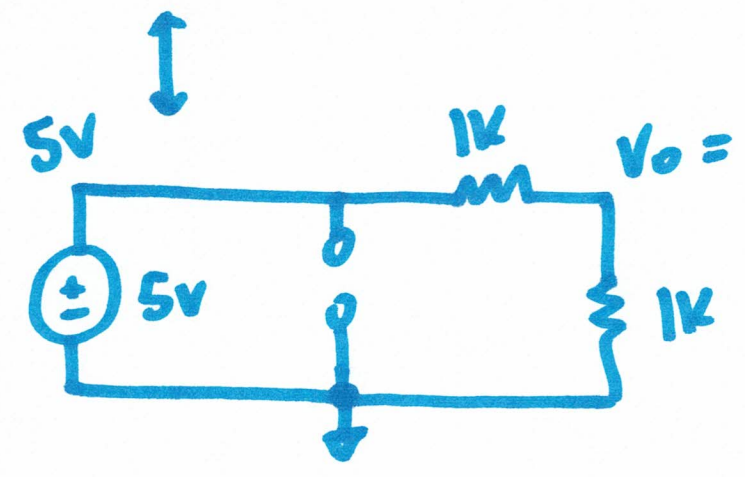
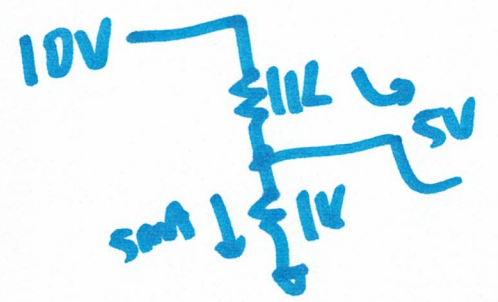
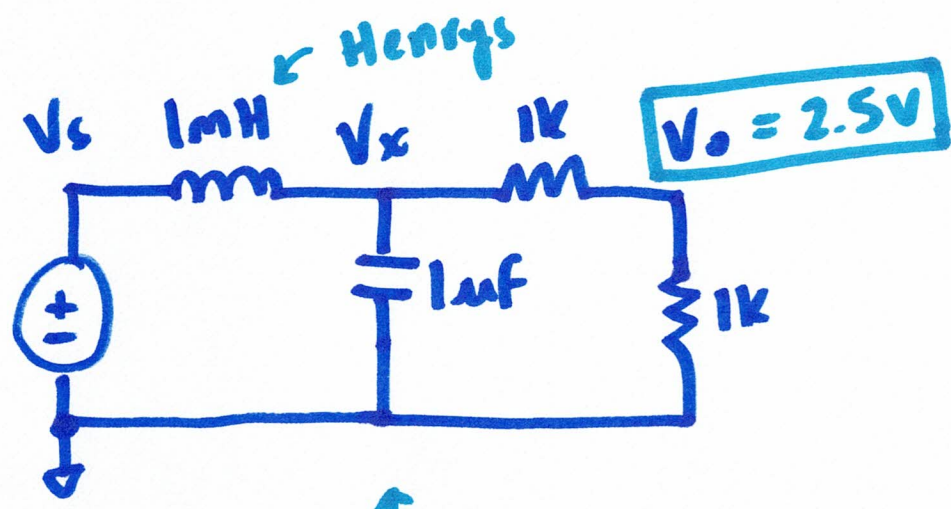
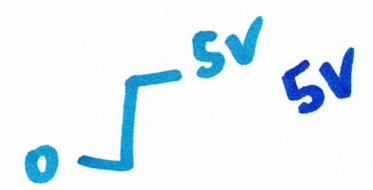
 in DC = short



$$V_L = L \cdot \frac{dI}{dt}$$



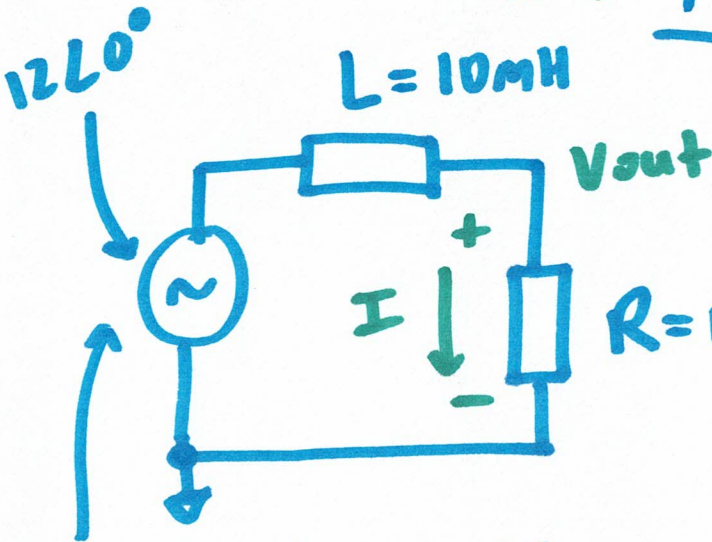
$$I_C = C \cdot \frac{dV}{dt}$$



$$Z = x + jy$$

# AC Steady State

$$2\pi f = 2\pi \cdot 200\text{kHz}$$



$$12\cos(2\pi ft) = V_{in}(t)$$

$$f = 200\text{kHz}$$

$$Z_R = R \angle 0^\circ$$

$$Z_L = \omega L \angle 90^\circ$$

$$Z_C = \frac{1}{\omega C} \angle -90^\circ$$

$$|Z_R| = \sqrt{x^2 + 0} = x$$

$$\phi = \tan^{-1}\left(\frac{0}{x}\right) = 0^\circ$$

$$|Z_L| = \sqrt{0 + y^2} = y$$

$$\phi = \tan^{-1}\left(\frac{y}{0}\right) = 90^\circ$$

$$I = \frac{12\angle 0^\circ}{16.06\text{k} \angle 51.5^\circ}$$

$$Z_T = Z_R + Z_L$$

$$j\omega L$$

$$Z_L = 10\text{mH} \cdot 2\pi \cdot 200\text{kHz} \cdot j$$

$$Z_L = j12.57\text{k}$$

$$Z_R = 10\text{k} \angle 0^\circ$$

$$Z_T = 10\text{k} + j12.57\text{k}$$

$$|Z_T| = 16.06\text{k}$$

$$\phi_{Z_T} = \tan^{-1}\left(\frac{12.57\text{k}}{10\text{k}}\right) = 51.5^\circ$$

$$Z_T = 16.06 \angle 51.5^\circ \text{ k}\Omega$$

$$= 0.75\text{m} \angle -51.5^\circ \text{ A} = I$$

# op-amp

