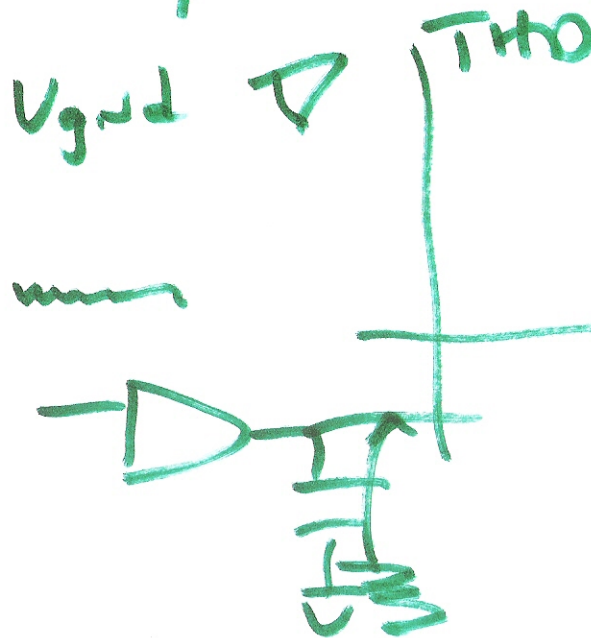
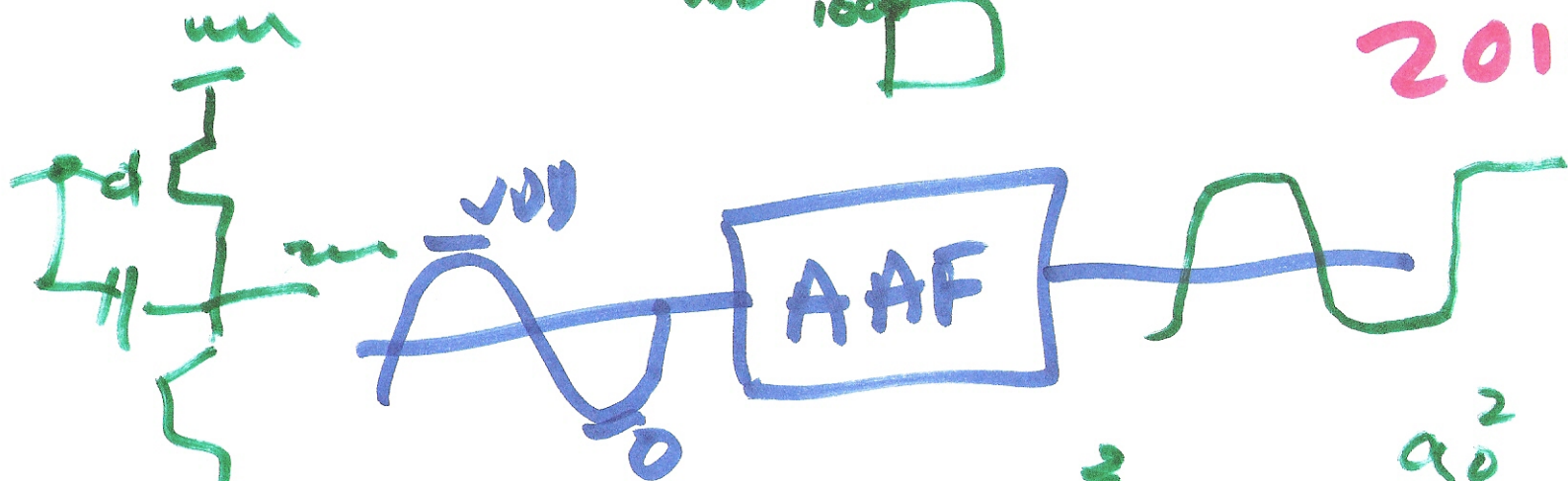
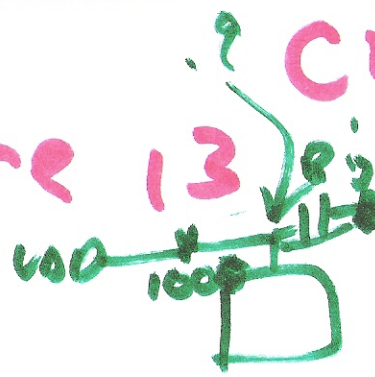


ECE 615 CMOS Mixed-Signal

Circuit Design

Lecture 13 OCT. 13, 2010



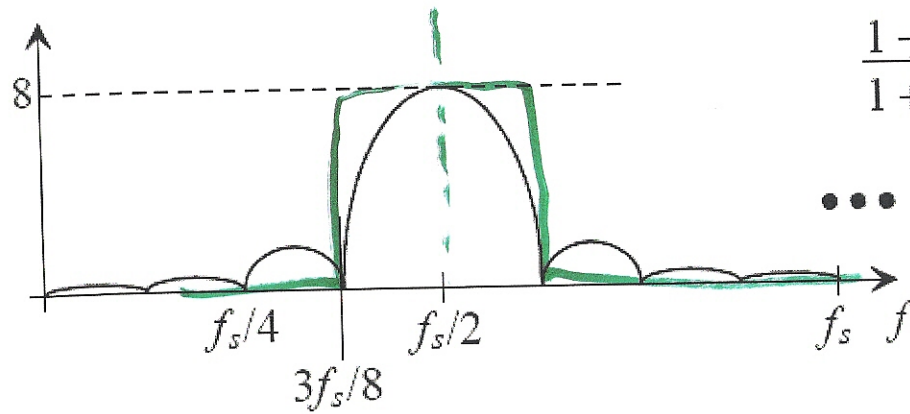
$$\sum_{n=1}^{\infty} \frac{1}{r_n} = \frac{g_0^2}{g_1^2 + g_2^2 + \dots}$$

$$\sum_{n=1}^{\infty} \frac{1}{r_n} = \frac{g_0^2}{g_1^2 + g_2^2 + \dots}$$

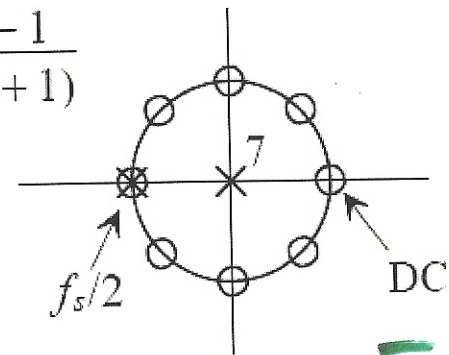
INPUT Amplitude

1)

.99532



$$\frac{1 - z^{-8}}{1 + z^{-1}} = \frac{z^8 - 1}{z^7(z + 1)}$$



Integers!

Figure 4.19 A highpass filter implementation using a comb filter.

comb filter followed
by a resonator

2)

$K = 8$

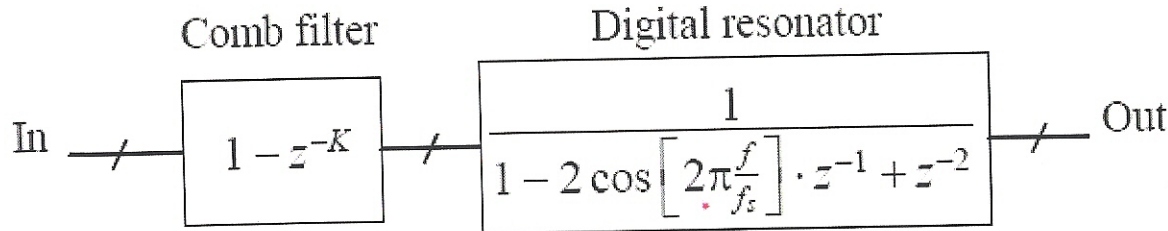
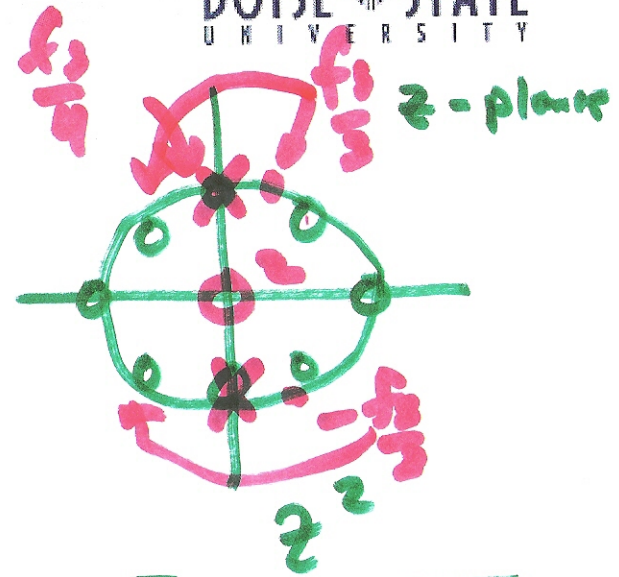


Figure 4.20 Implementing a sinc-shaped bandpass filter.

$$\frac{1}{1 + z^{-2}} = \frac{z^2}{z^2 + 1} = \frac{z^2}{(z+j)(z-j)}$$

$$\frac{1}{1 - z^{-1} + z^{-2}} = \frac{z^2}{z^2 + z + 1}$$

change sign

$$\frac{-1 \pm \sqrt{1-4}}{2} = \frac{-1 \pm \sqrt{-3}}{2} = -\frac{1}{2} \pm \frac{\sqrt{3}}{2}j \quad K=12$$

$$= \frac{z^2}{\left(z + \frac{1}{2} - \frac{\sqrt{3}}{2}j\right)\left(z + \frac{1}{2} + \frac{\sqrt{3}}{2}j\right)}$$

3)

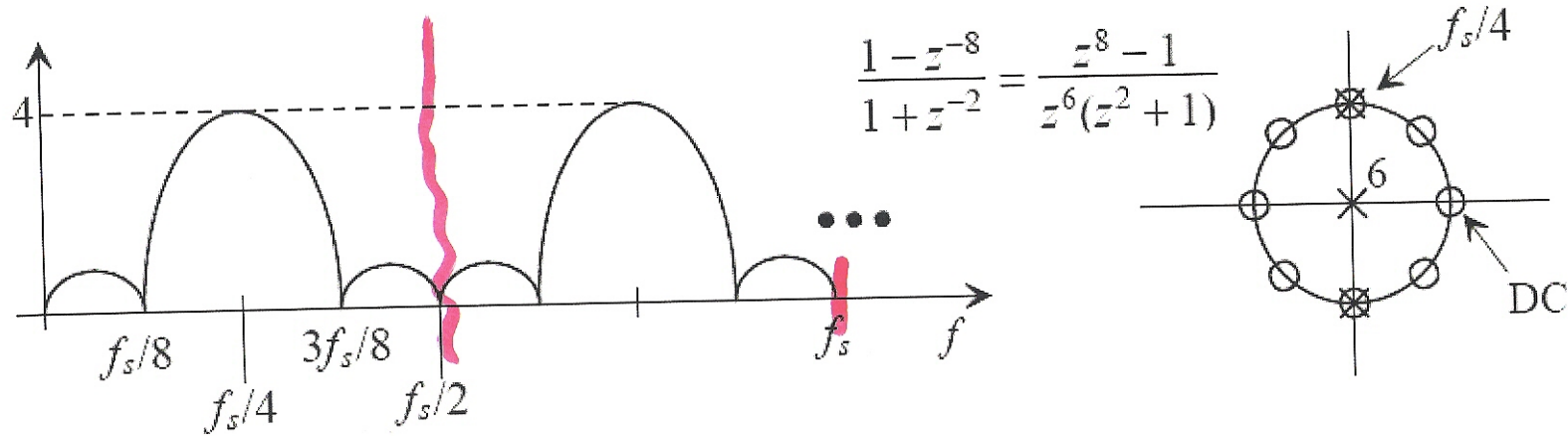


Figure 4.21 A bandpass filter implementation using a comb filter and digital resonator.

4)

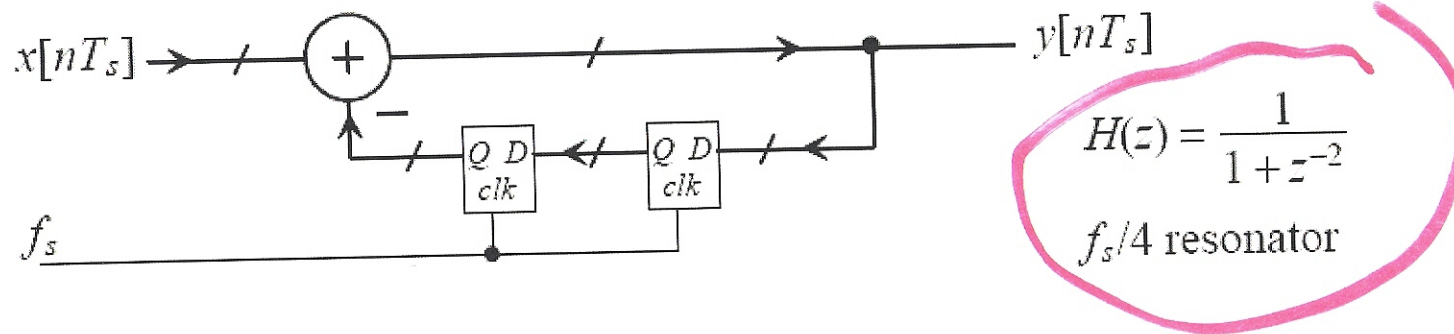
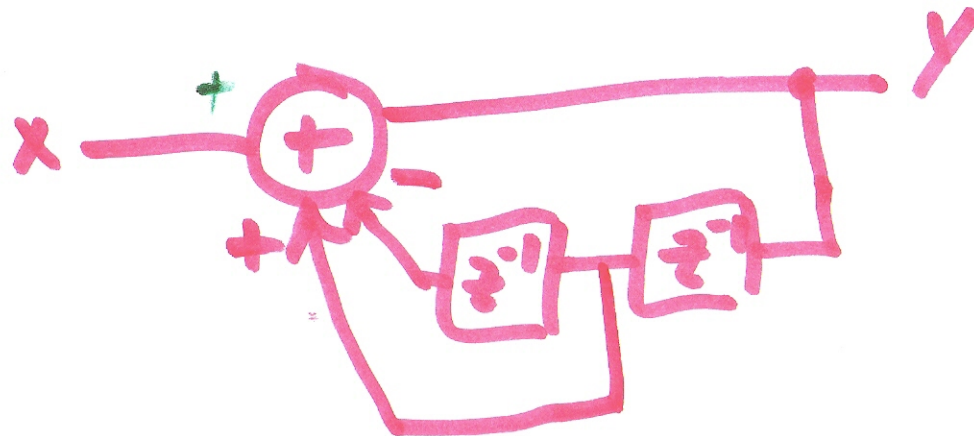


Figure 4.23 Implementation of a digital resonator.

$$\frac{1}{1-z^{-1}+z^{-2}}$$

$$x + yz^{-1} - yz^{-2} = y$$

$$\frac{y}{x} = \frac{1}{1-z^{-1}+z^{-2}}$$



5)

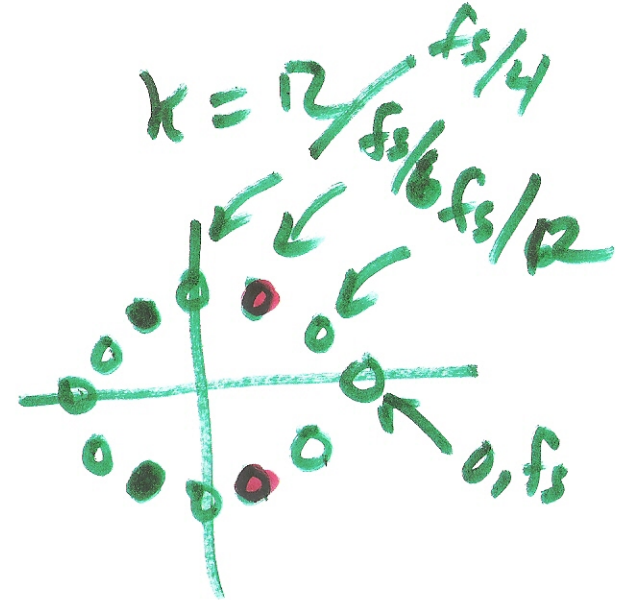
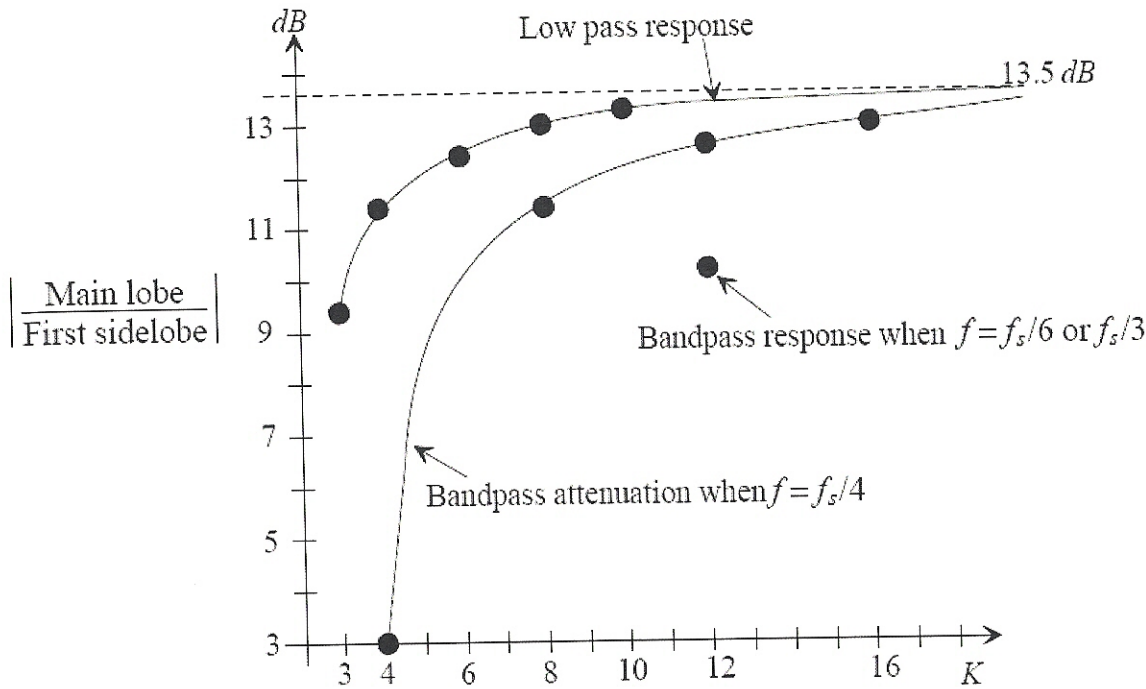
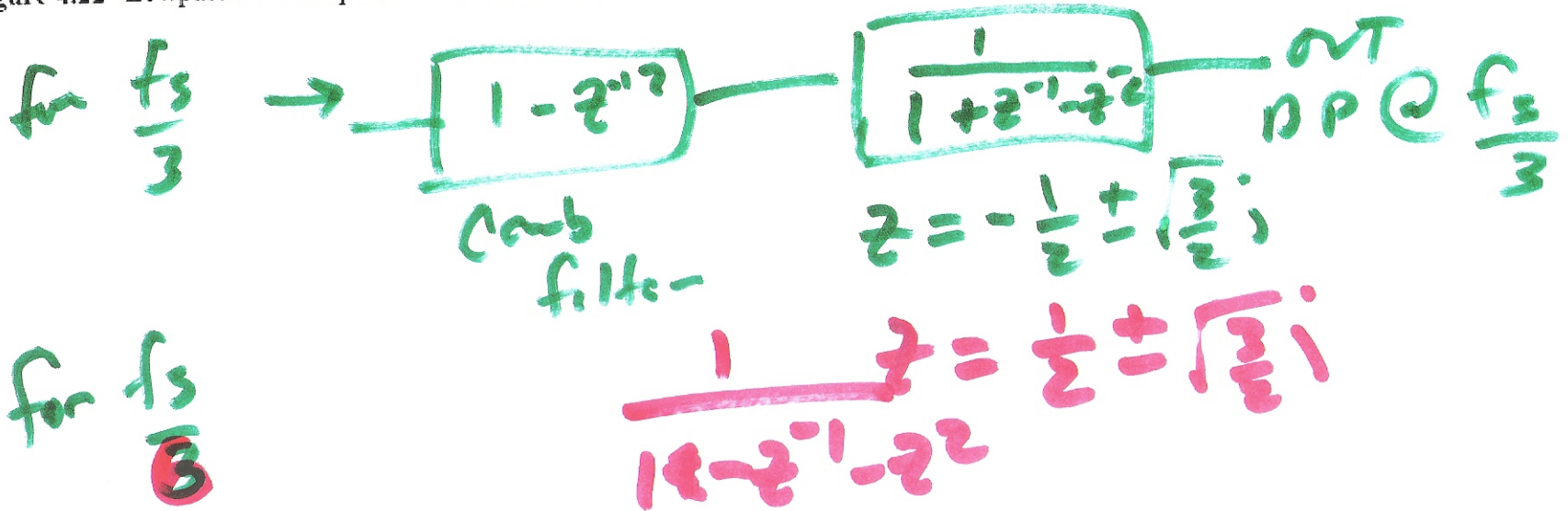


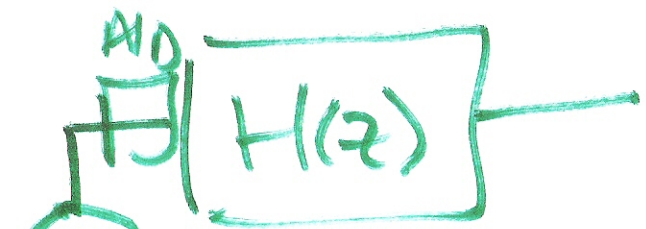
Figure 4.22 Lowpass and bandpass filter attenuation versus number of comb filter zeroes, K.



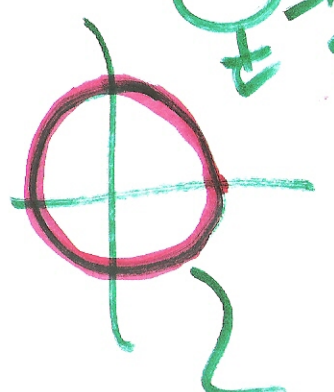
b)

$$\frac{1}{1 - 2z^{-1} + z^{-2}} = \frac{z^2}{z^2 - 2z + 1}$$

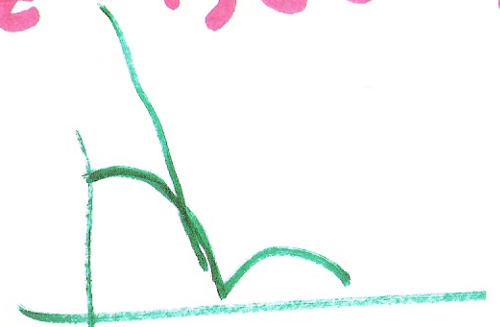
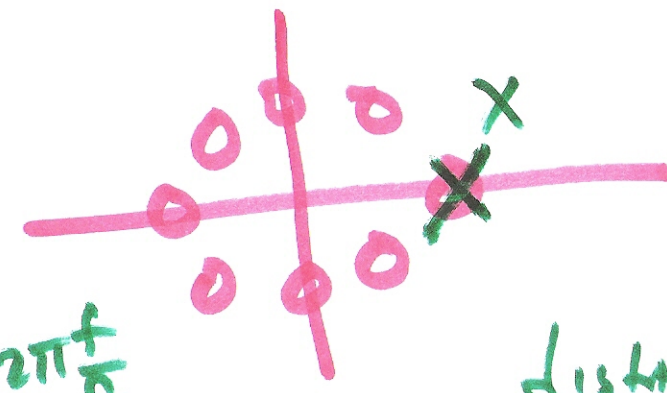
iv



$$= \frac{z^2}{(z-1)(z-1)}$$



$$z = e^{j2\pi \frac{f}{f_s}}$$



$\frac{\text{distance to zeros}}{\text{distance to poles}}$

\gg

$$\frac{1}{1 - \frac{1}{2}z^{-1} + z^{-2}} = \frac{z^2}{z^2 - \frac{1}{2}z + 1}$$

$$z = \frac{\frac{1}{2} \pm \sqrt{\frac{1}{4} - 4}}{2}$$

$$= \frac{1}{4} \pm j \cdot \sqrt{\frac{1}{8} - 1}$$
$$= \frac{1}{4} \pm j \sqrt{\frac{15}{8}}$$

e)

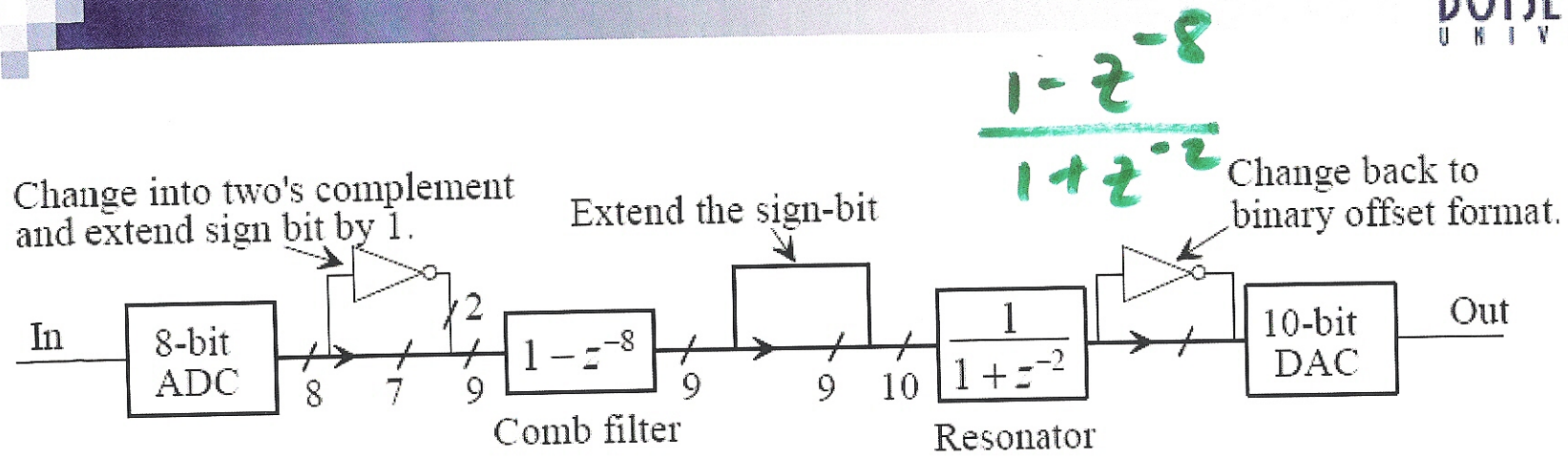
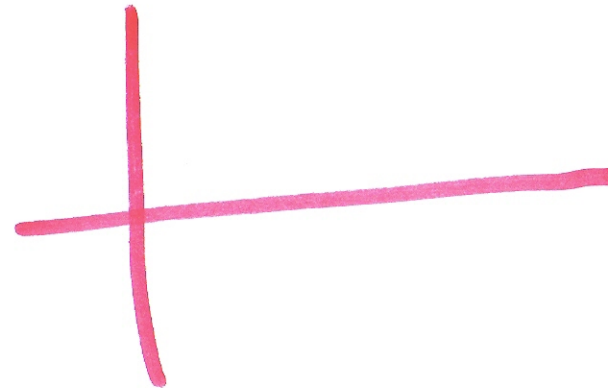


Figure 4.24 Digital filter sketch for Ex. 4.7.



9)

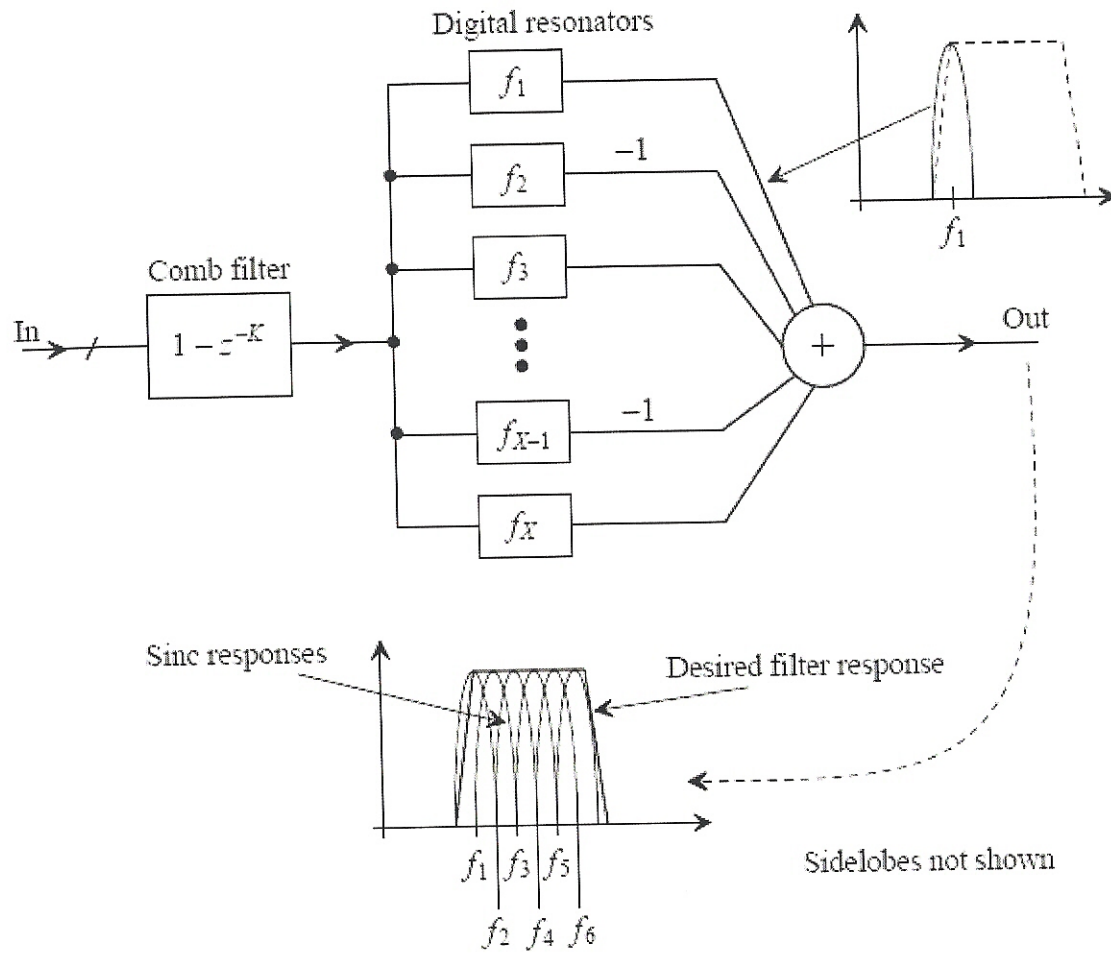


Figure 4.26 A frequency sampling filter.



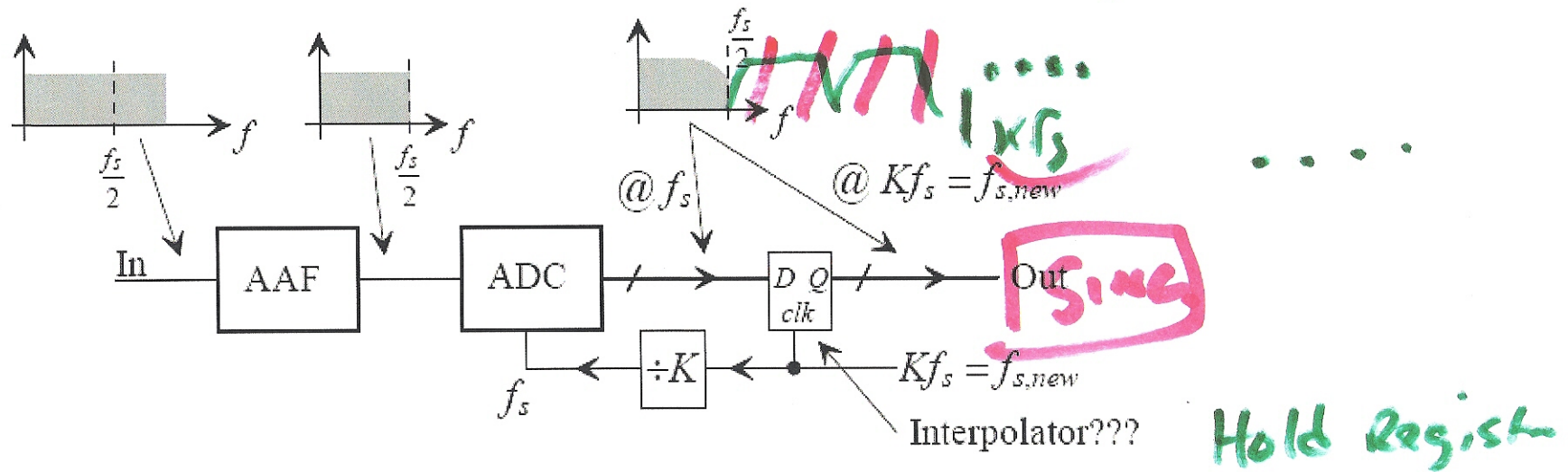


Figure 4.27 Interpolation using a hold register (see Sec. 2.1.5).

Sine filter



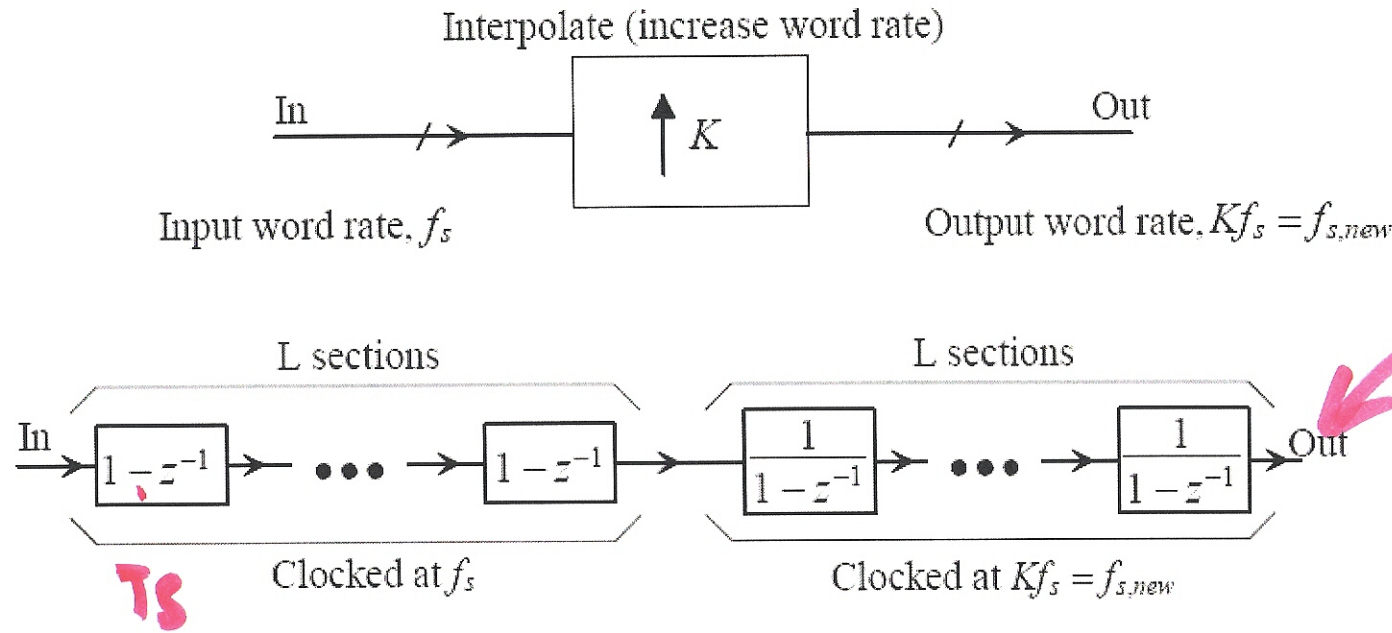


Figure 4.28 Interpolating using Sinc filters for image removal.

$k f_s$
 $\frac{T_s}{k} \Rightarrow f_s \cdot k$

 $k f_s$

$\left(\frac{1 - z^{-k}}{1 - z^{-1}} \right)^L$

 $@ f_s$

12)

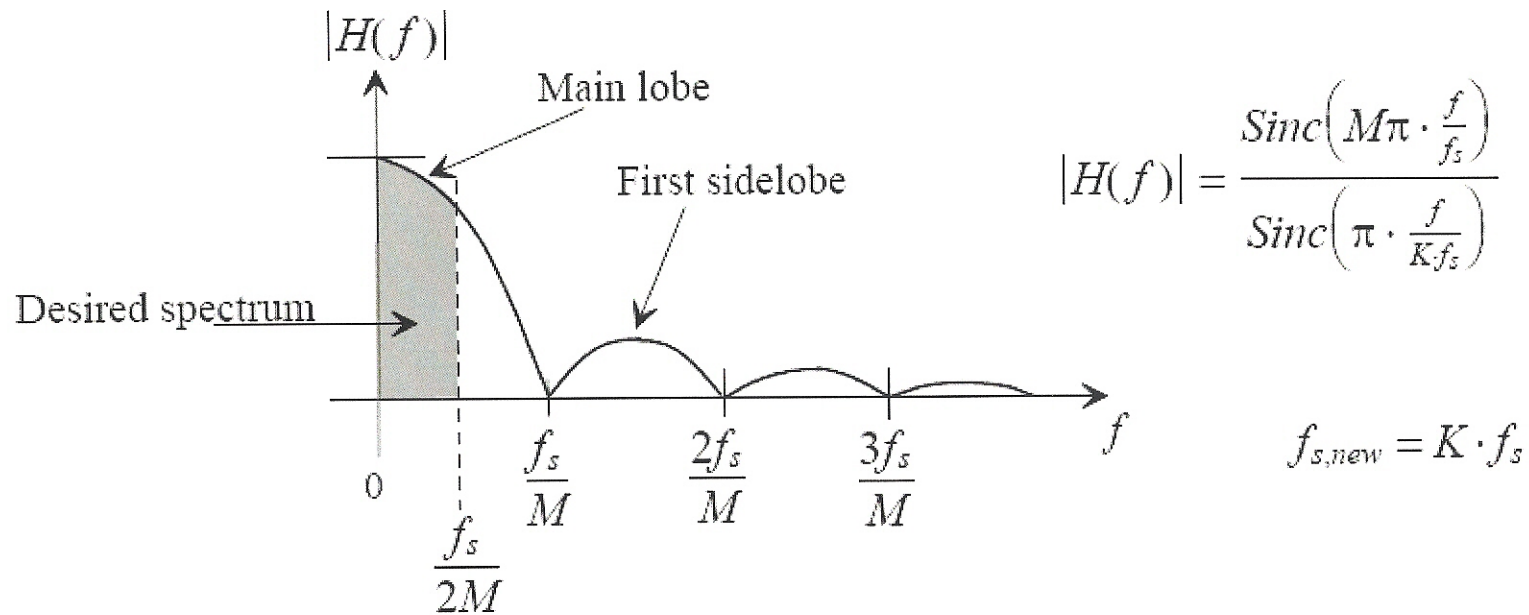


Figure 4.31 Frequency response image removal filter using a Sinc interpolator, Fig. 4.30.